

Multi-objective Design of Active Remediation with Natural Attenuation Under Parameter Uncertainty

Amy B. Chan-Hilton, Ph.D.
Satyajeet Iyer

Florida A&M University – Florida State University
College of Engineering
Civil and Environmental Engineering
Tallahassee, FL



Motivation

- Need for identifying cost-effective and reliable groundwater remedial designs
- Increased use of natural attenuation (NA), often combined with active remediation
- Natural variability of and limited data on system parameters, leading to difficulty in:
 - Predicting remediation effectiveness
 - Estimating remediation costs
 - Designing remediation strategies

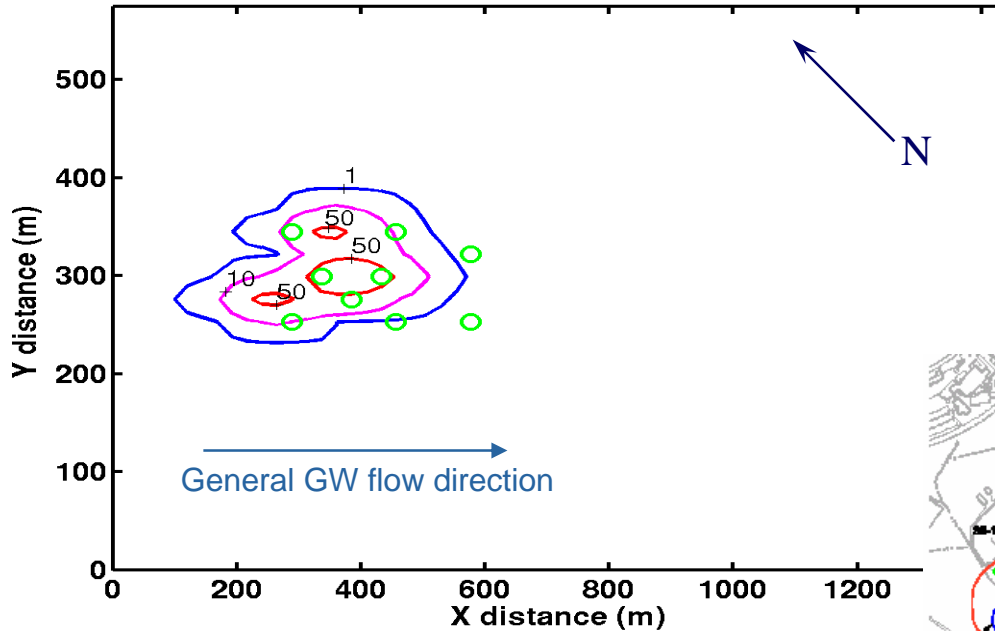


Research Objectives

- Develop and apply Enhanced Multi-Objective Robust Genetic Algorithm (EMRGA) to optimize groundwater remediation designs
- Find cost effective and reliable remediation designs while considering uncertainty
- Analyze effects of parameter uncertainty on optimal design of combined natural attenuation/active remediation systems

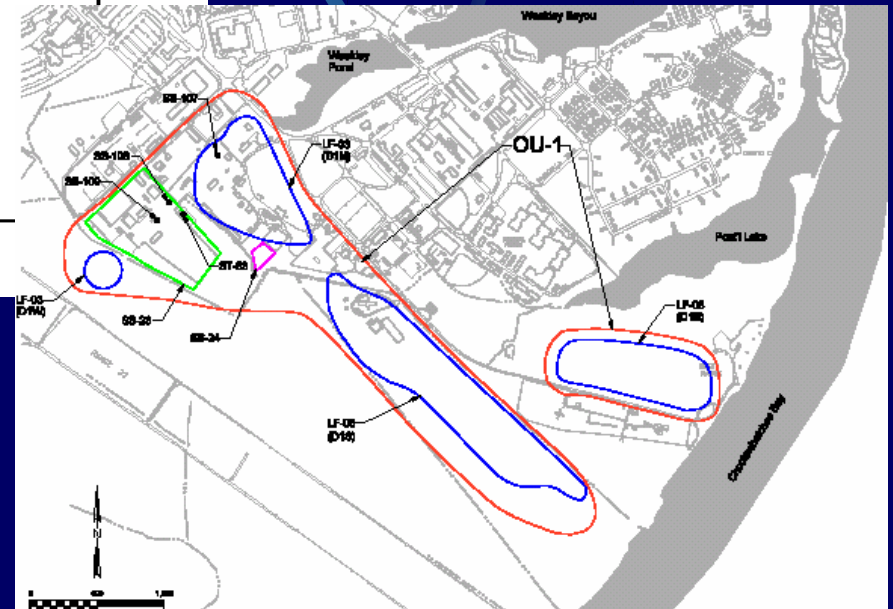


Study Site



- Developed study site based on OU-1 site at Eglin AFB, Florida

- NA observed at site
- Contaminants: Benzene, TCE, VOCs, PCBs



Remediation Optimization

- Use combination of active remediation and NA to reduce benzene concentrations:
 - Year 1: active remediation (pump and treat)
 - Years 2-5: natural attenuation (NA)
- Identify optimal set up extraction wells to achieve multiple remediation goals
- Account for uncertainty/heterogeneity in:
 - Hydraulic conductivity (K)
 - Hydraulic gradient (dh/dx)
 - First-order decay rate (k)

Optimization Problem

■ Two conflicting objectives:

- Minimize total active remediation costs:

$$\min \text{Cost} = G_{\text{pump}} + G_{\text{carbon}} + G_{\text{cap,treat}} + G_{\text{cap,well}}$$

- Minimize maximum concentration:

$$\min(C_{\max})$$

■ Constraints on:

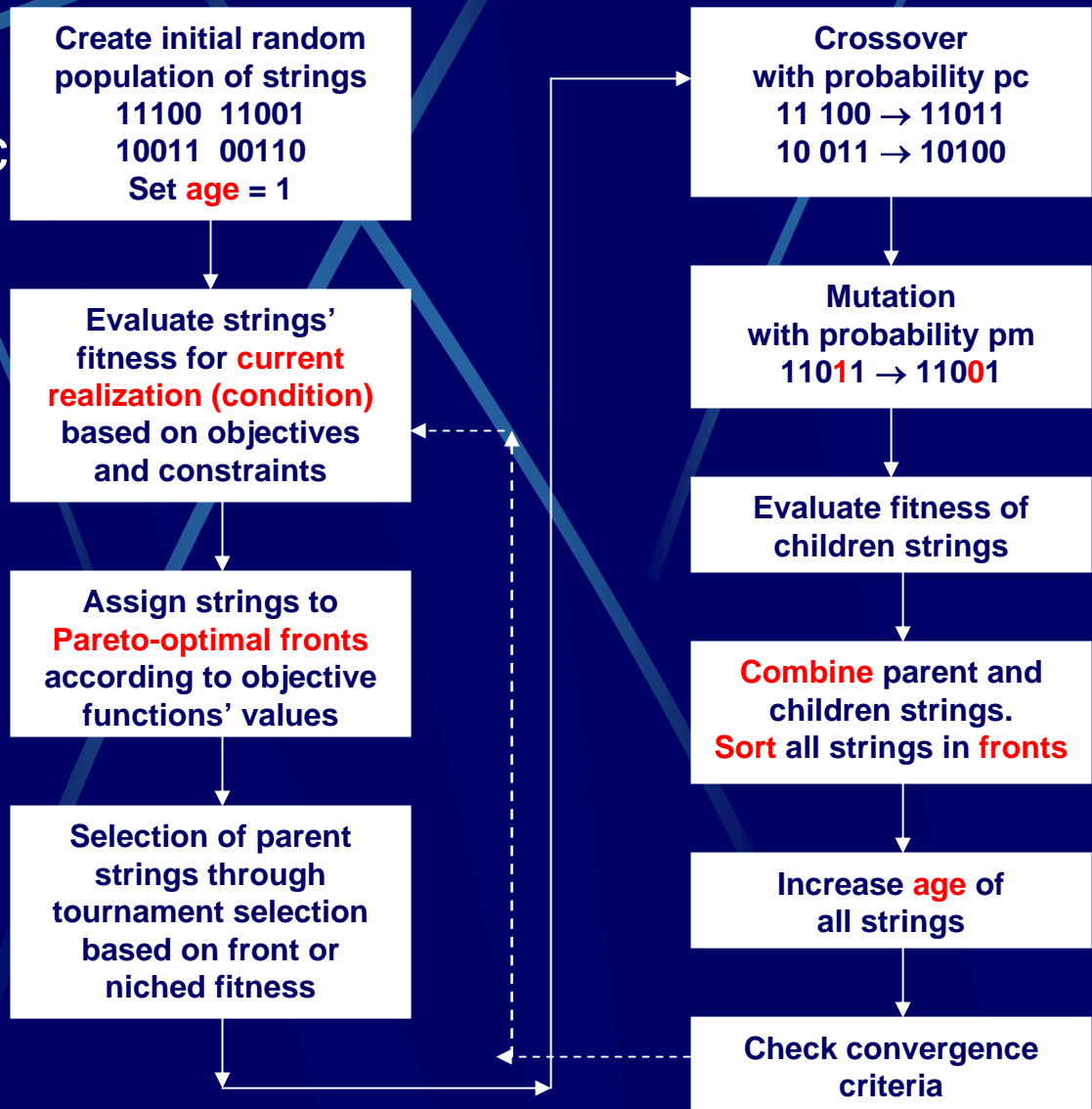
- Hydraulic heads: $h_j \geq h_{\min} \quad \forall j \in 1, N$

- Pumping rates: $Q_{\min} \leq Q_k \leq Q_{\max} \quad \forall k \in 1, K$



Optimization Approach

- Enhanced multi-objective robust genetic algorithm (EMRGA)
 - GW flow and contaminant transport model
 - Spatially-correlated random field generator
- Accounts for parameter uncertainty
- Evolves trade-off curves (Pareto-optimal sets)



Numerical Experiments

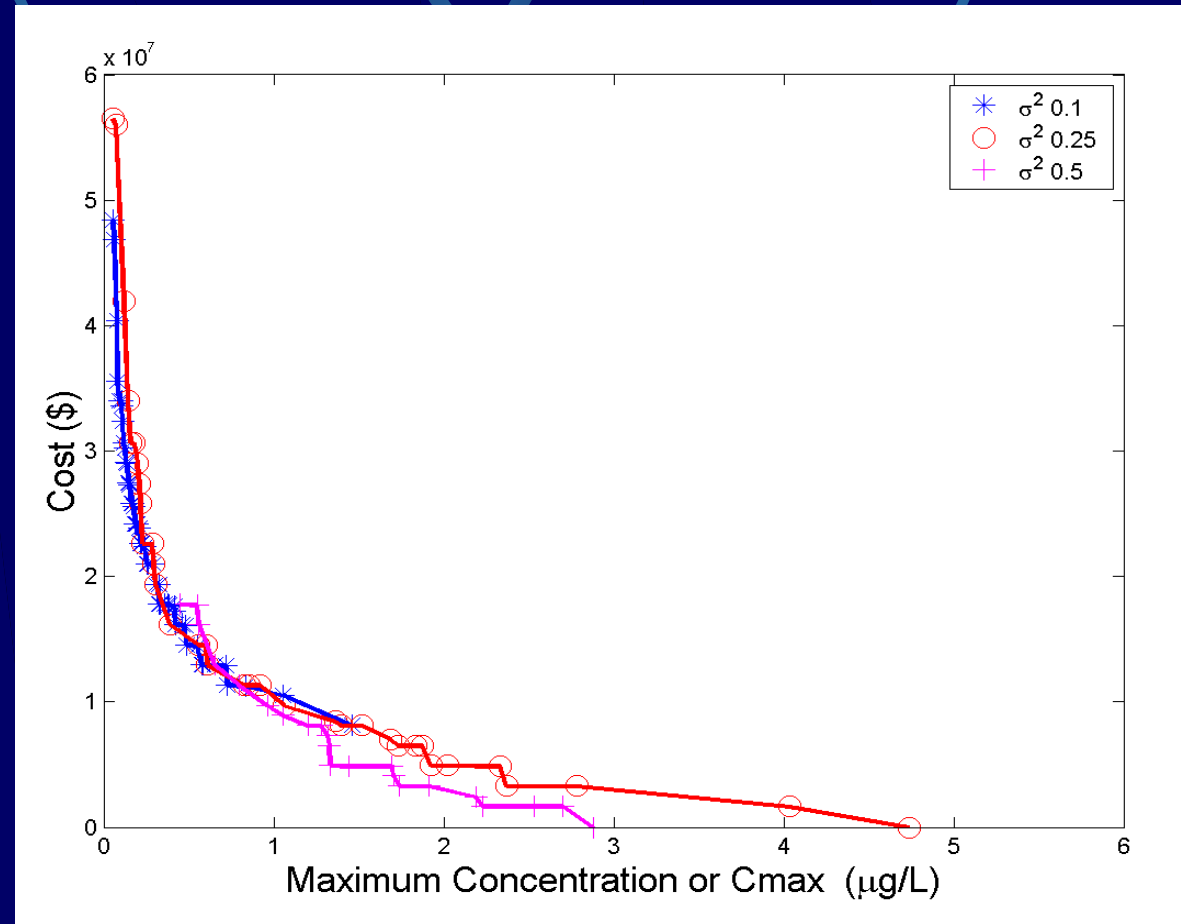
Same average value of each parameter for all cases

Hydraulic Conductivity (K)	Hydraulic Gradient (dh/dx)	Decay rate (k)
$\sigma^2 = 0.1$ $\sigma^2 = 0.25$ $\sigma^2 = 0.5$	Assumed known ($h_1 = 32\text{ft}$, $h_2 = 23\text{ ft}$; $dh/dx = 0.00625$)	Assumed known ($k = 0.001/\text{day}$)
$\sigma^2 = 0.1$ $\sigma^2 = 0.5$	Low range ($h_1=31$ to 33 ft) Moderate ($h_1=30$ to 34 ft) High range ($h_1=28$ to 36 ft)	Assumed known ($k = 0.001/\text{day}$)
$\sigma^2 = 0.1$ $\sigma^2 = 0.5$	Assumed known ($h_1 = 32\text{ft}$, $h_2 = 23\text{ ft}$; $dh/dx = 0.00625$)	Low range ($k=5e-4$ to $1.5e-3$) Moderate ($k=1e-4$ to $1e-2$) High range ($k=5.6e-5$ to $1.8e-2$)



Results: Uncertainty in K

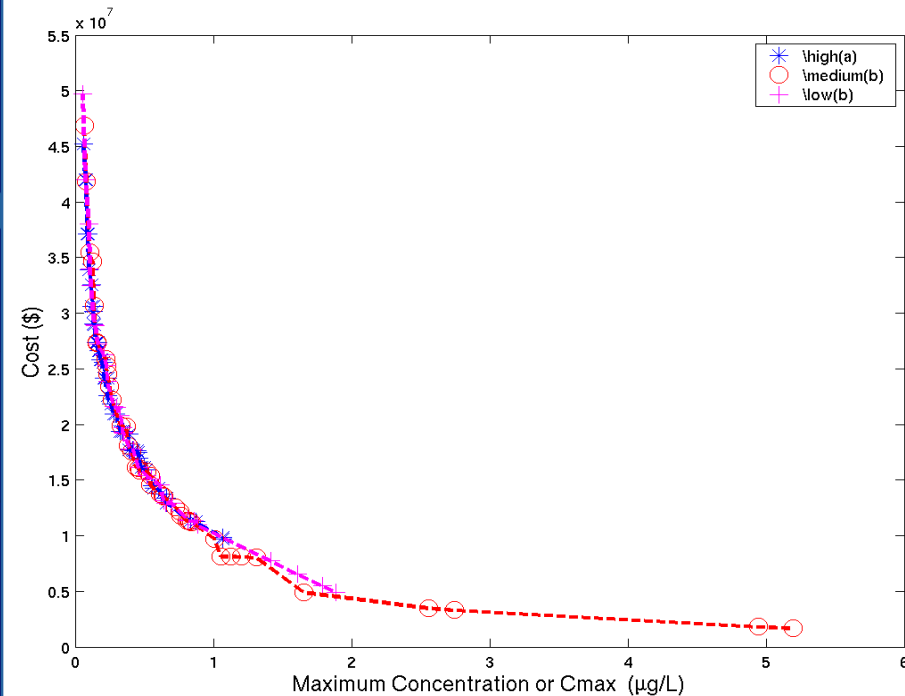
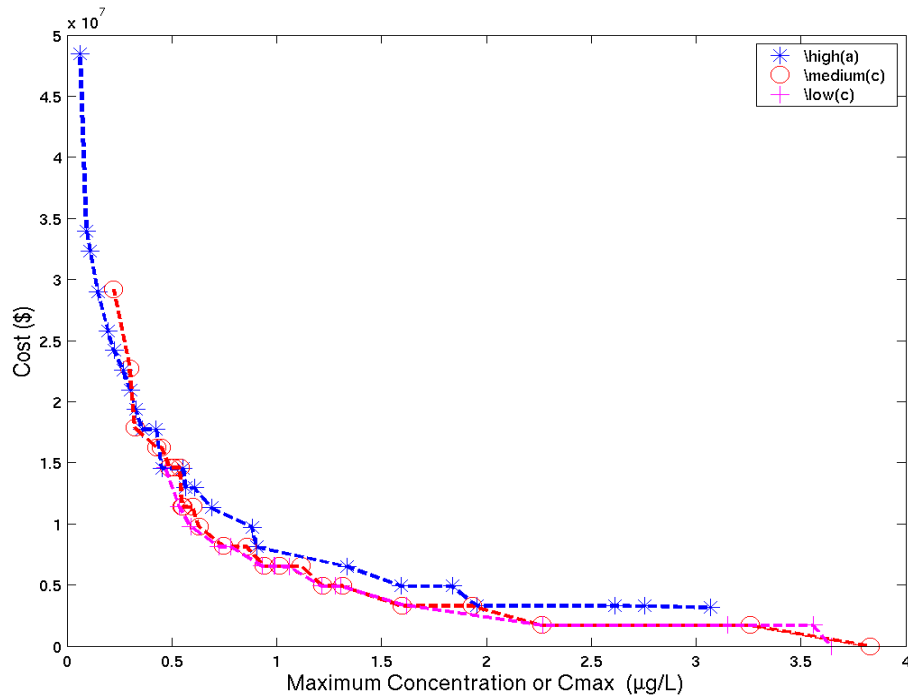
- Optimal solution represented by trade-off curve between conflicting goals
- Each point represents an optimal design



Uncertainty in dh/dx and K

High K uncertainty

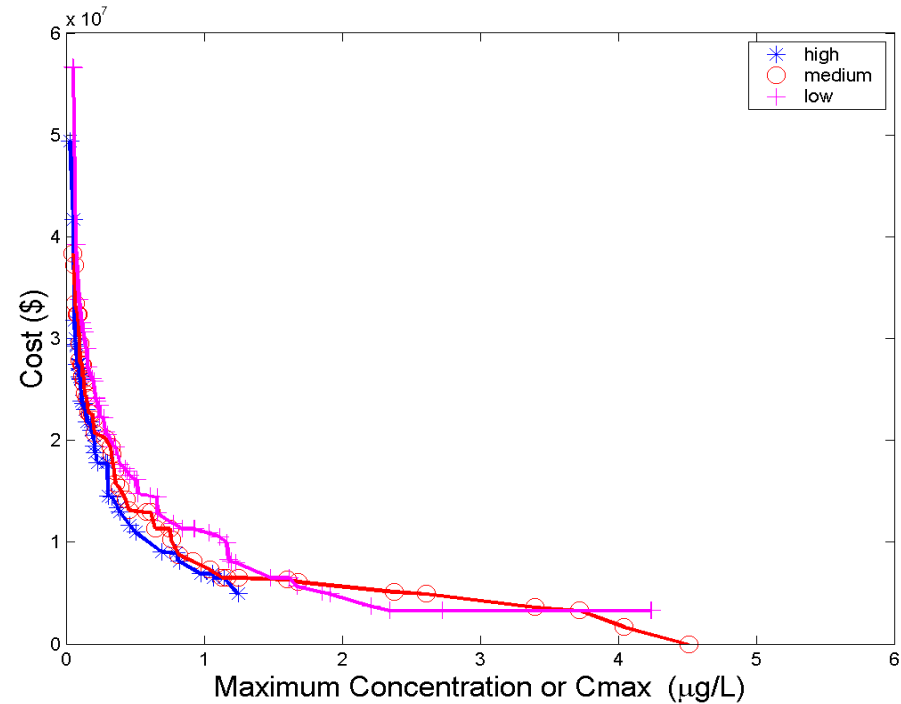
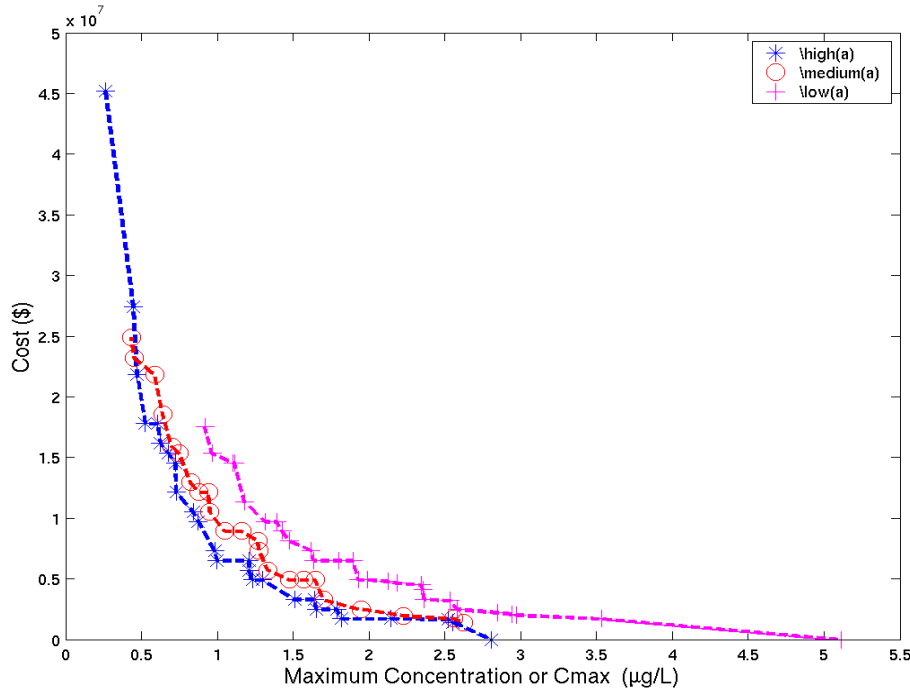
Low K uncertainty



Uncertainty in k and K

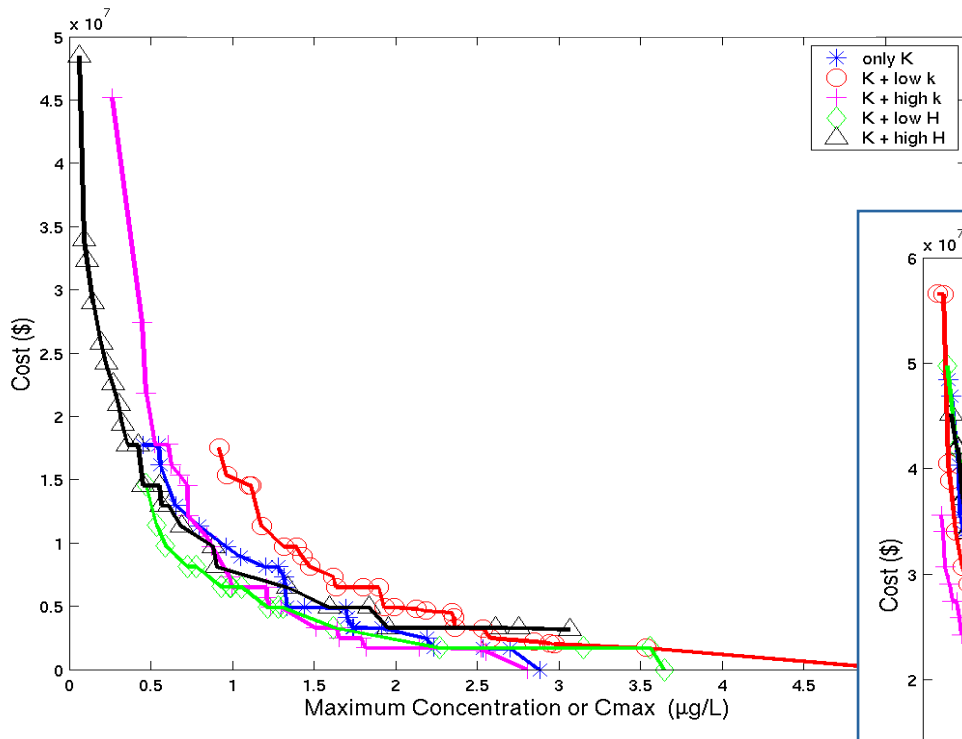
High K uncertainty

Low K uncertainty

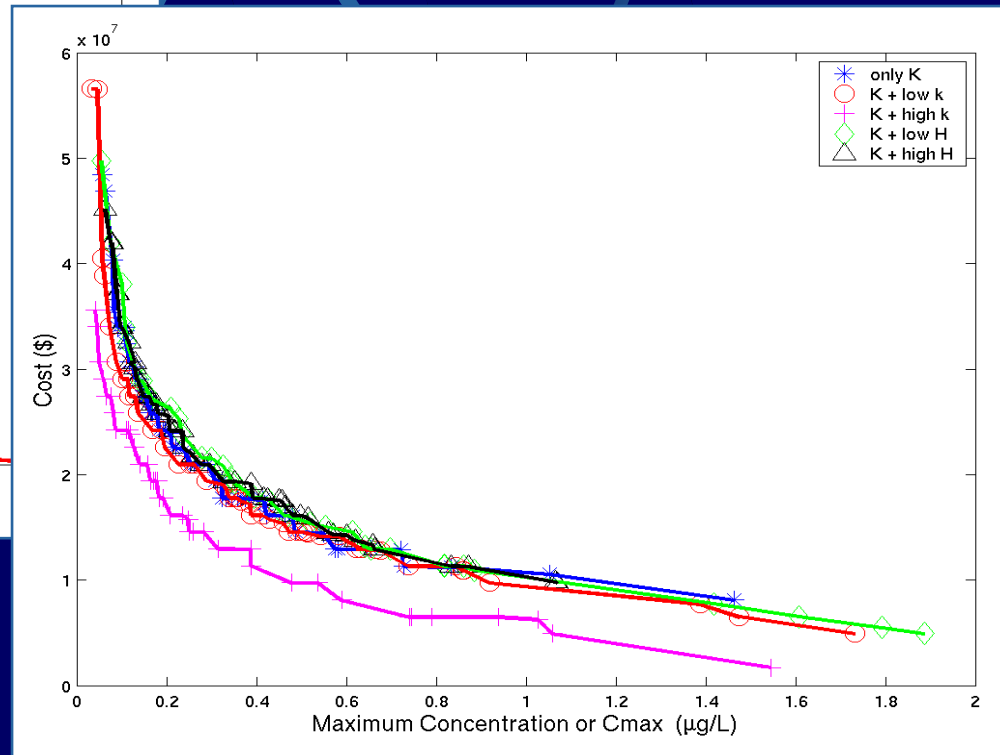


Comparison: All Cases

High K uncertainty

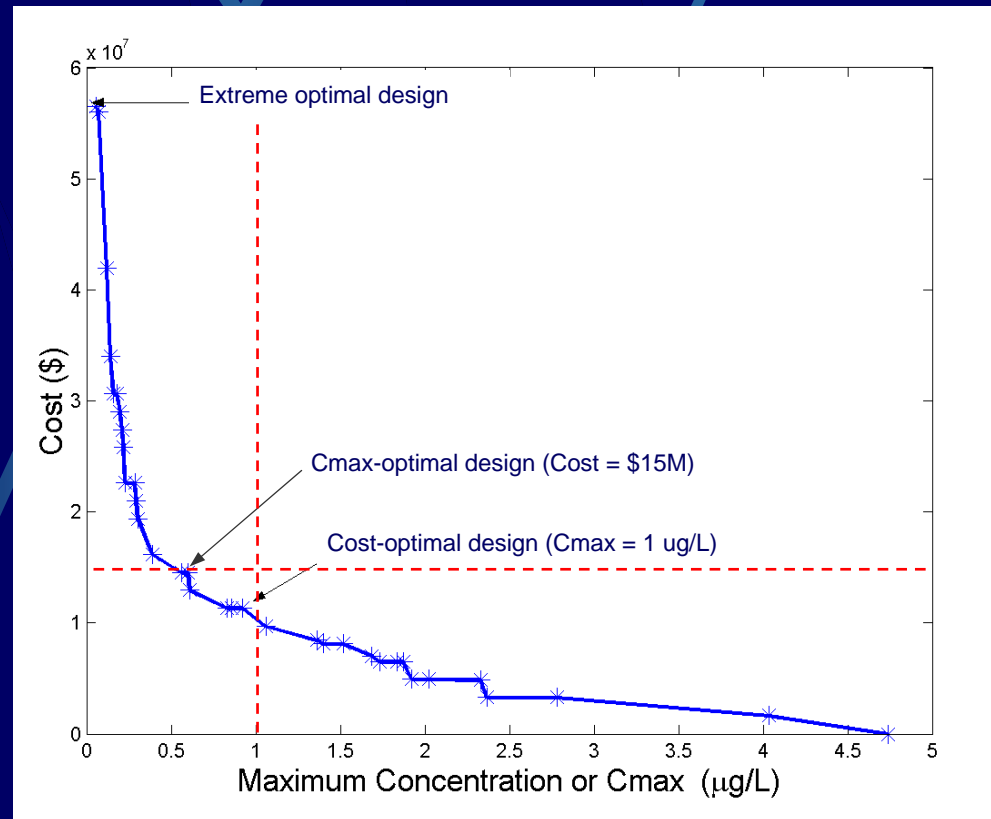


Low K uncertainty



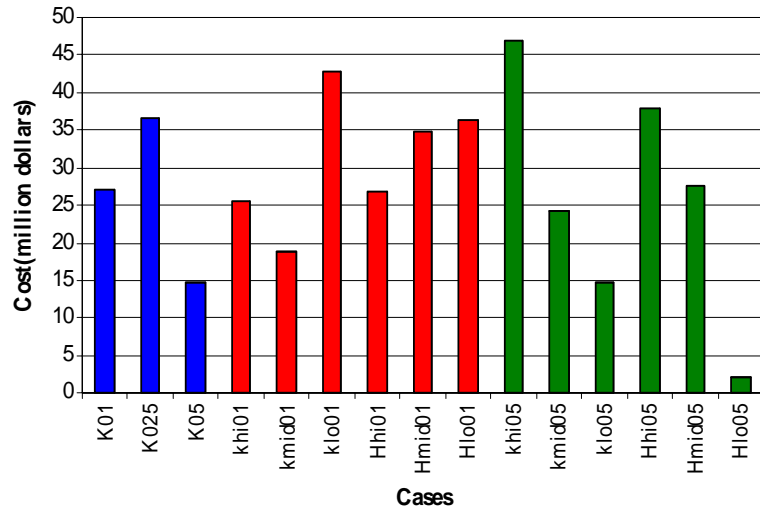
Analysis of Optimal Designs

- For each case, analyze selected designs:
 - Extreme optimal design
 - Cost-optimal design
 - Cmax-optimal design
- Analysis through Monte-Carlo simulations
- Performance measures:
 - Cost
 - Maximum concentration
 - Reliability

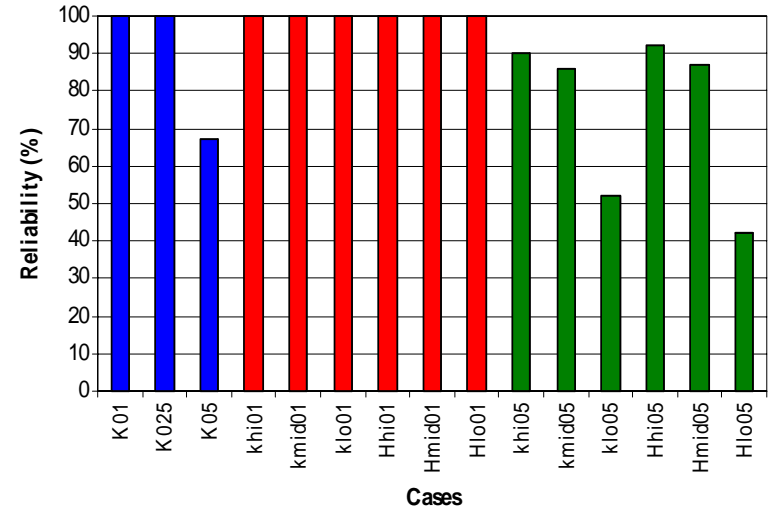


Extreme Optimal Designs

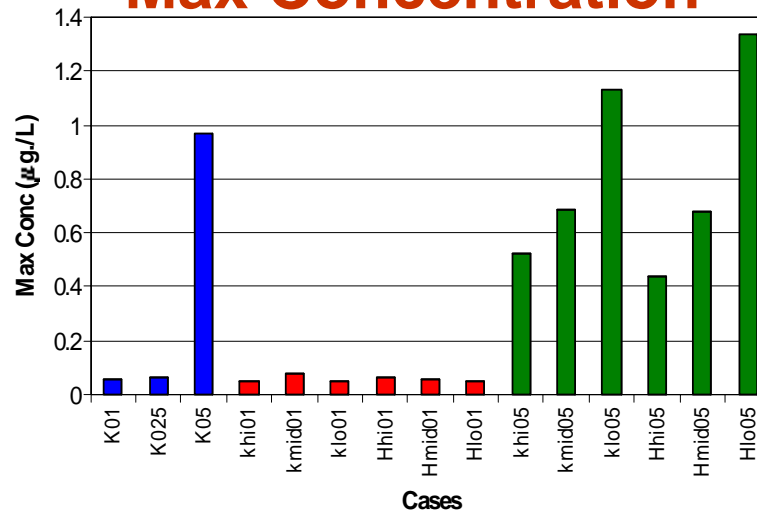
Cost



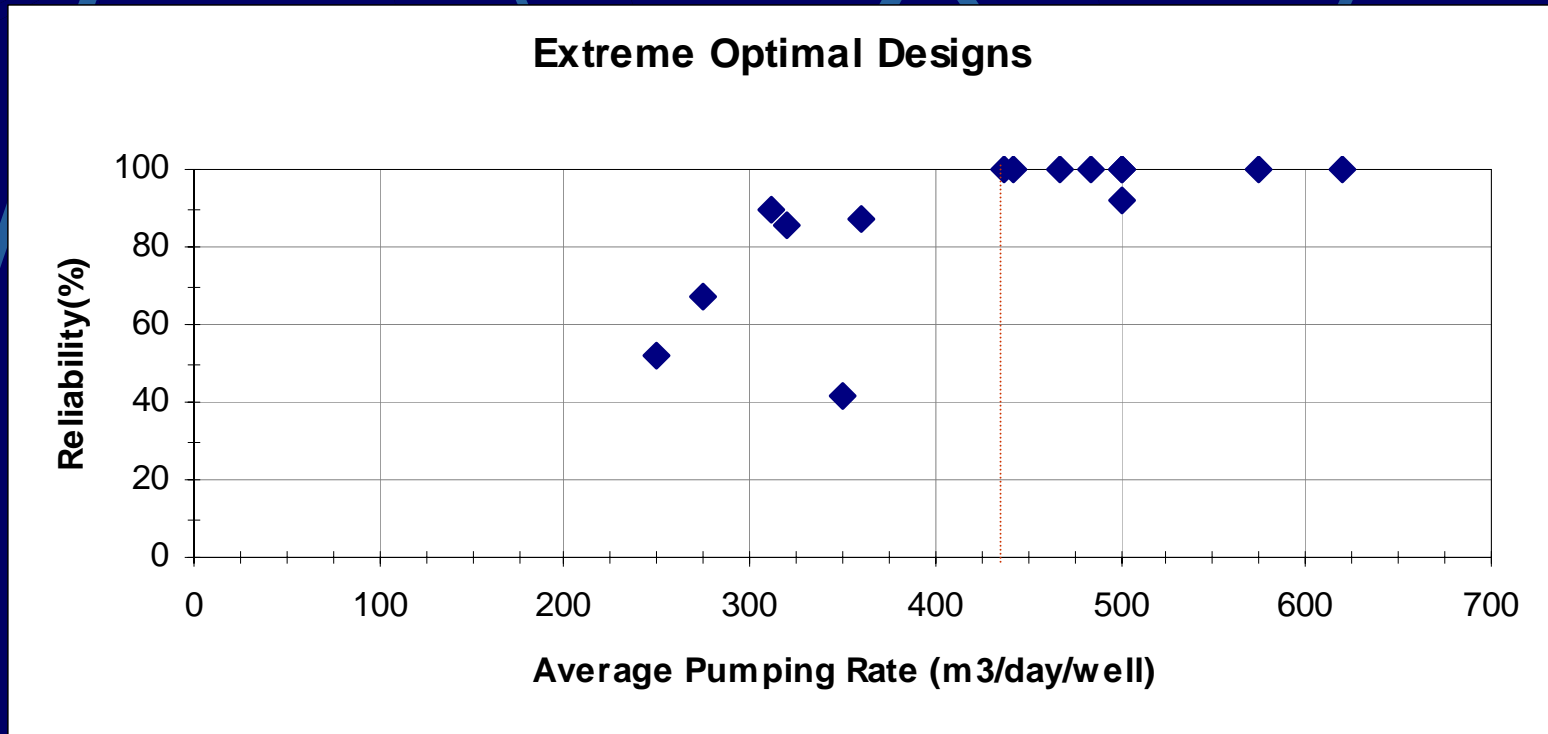
Reliability



Max Concentration

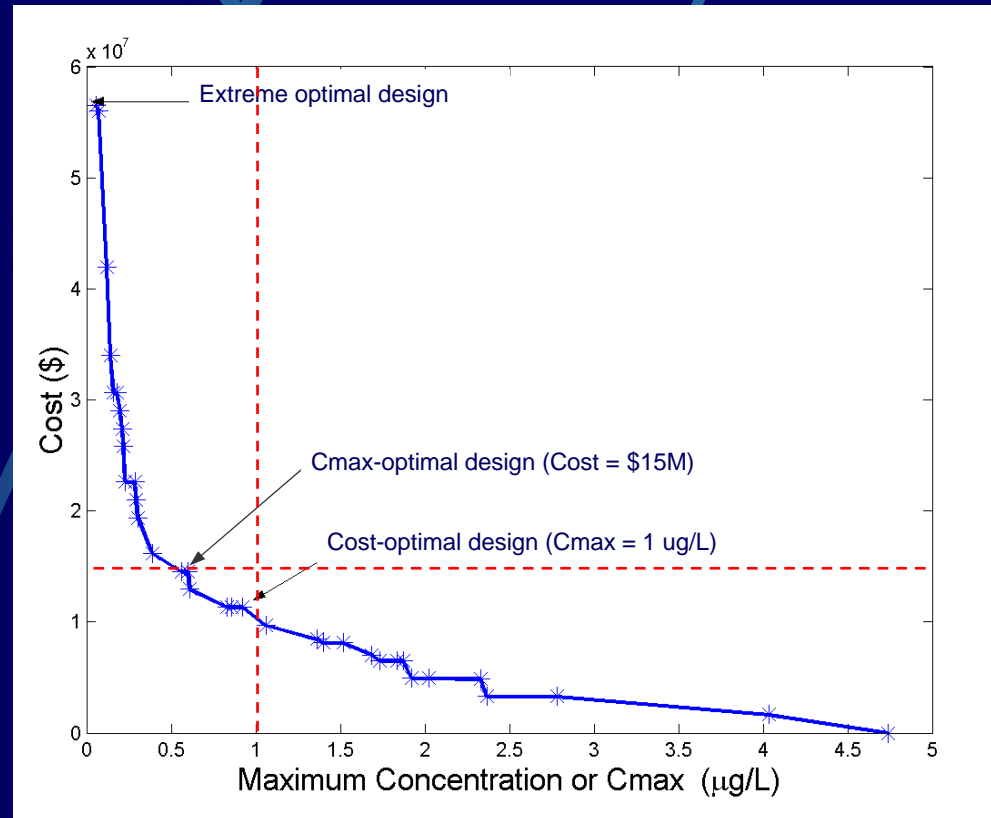


Threshold Average Pumping Rate?



Analysis of Optimal Designs

- For each case, analyze selected designs:
 - Extreme optimal design
 - Cost-optimal design
 - Cmax-optimal design
- Analysis through Monte-Carlo simulations
- Performance measures:
 - Cost
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 - Reliability

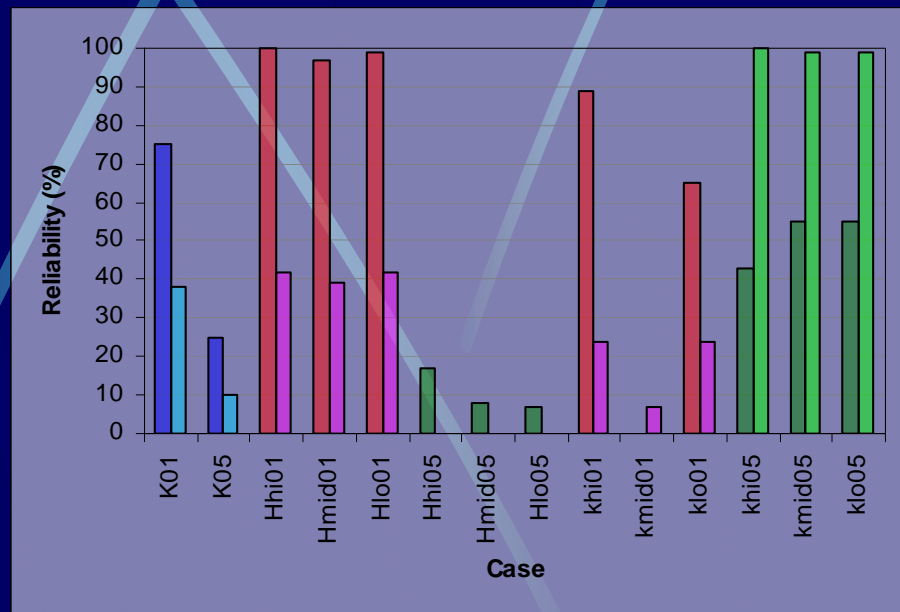
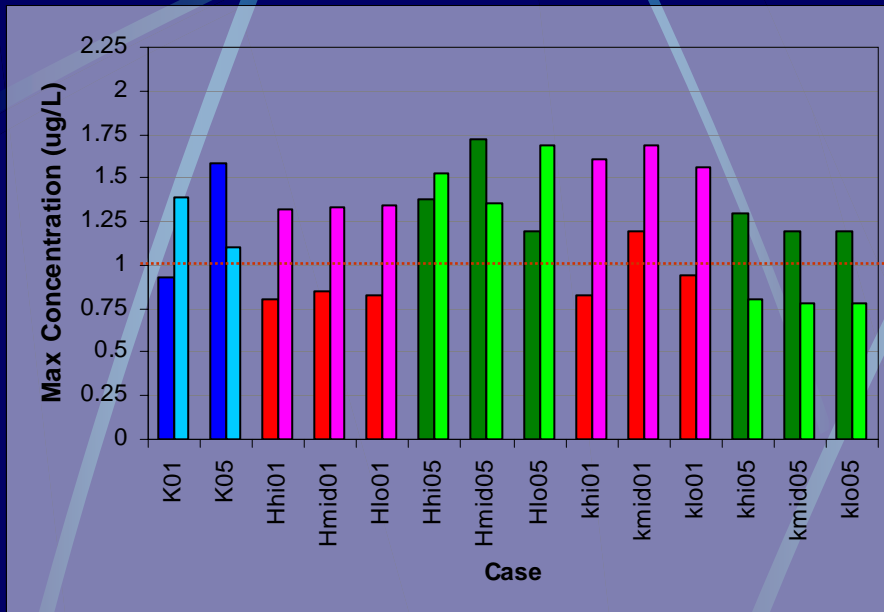


Cost-Optimal Designs

$C_{max} = 1 \text{ ug/L}$

Max Concentration

Reliability



All cases evaluated on same K uncertainty scenarios

Left bars: Analyzed using low K variance ($\sigma^2 = 0.1$)

Right bars: Analyzed using high K variance ($\sigma^2 = 0.5$)

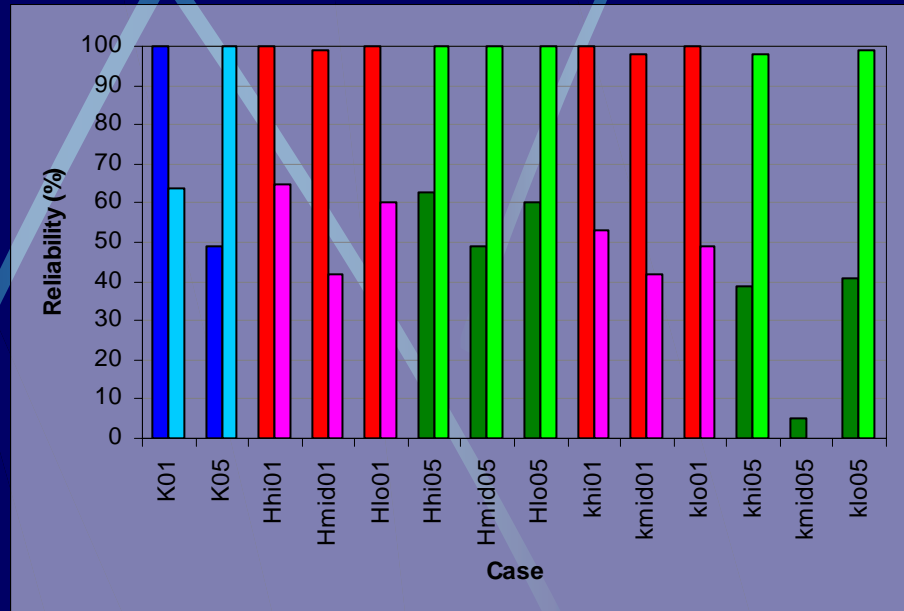
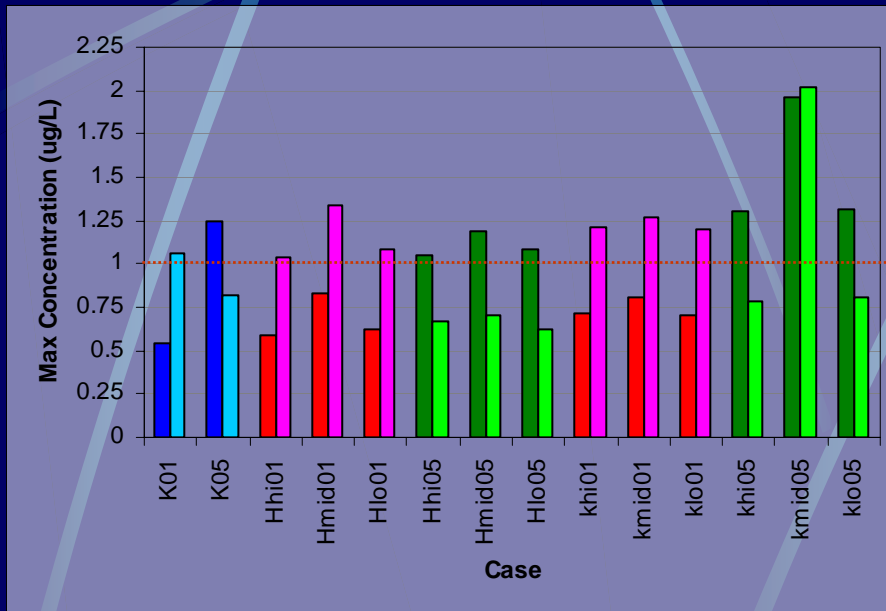


Cmax-Optimal Designs

Cost = \$15M

Max Concentration

Reliability



All cases evaluated on same K uncertainty scenarios

Left bars: Analyzed using low K variance ($\sigma^2 = 0.1$)

Right bars: Analyzed using high K variance ($\sigma^2 = 0.5$)



Conclusions

- As uncertainty and heterogeneity increases:
 - Fewer designs with lower maximum concentrations
 - Differences in trade-off curves increase
- Consider parameter uncertainty
 - Hydraulic conductivity most important
 - Multiple parameter uncertainty significant for cases with high K uncertainty
- Assuming more uncertainty/heterogeneity may not produce more robust designs
 - Quantify uncertainty and parameter variability

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Amy B. Chan-Hilton

Florida A&M University – Florida State University

College of Engineering

Civil and Environmental Engineering

Tallahassee, FL

850/410.6121

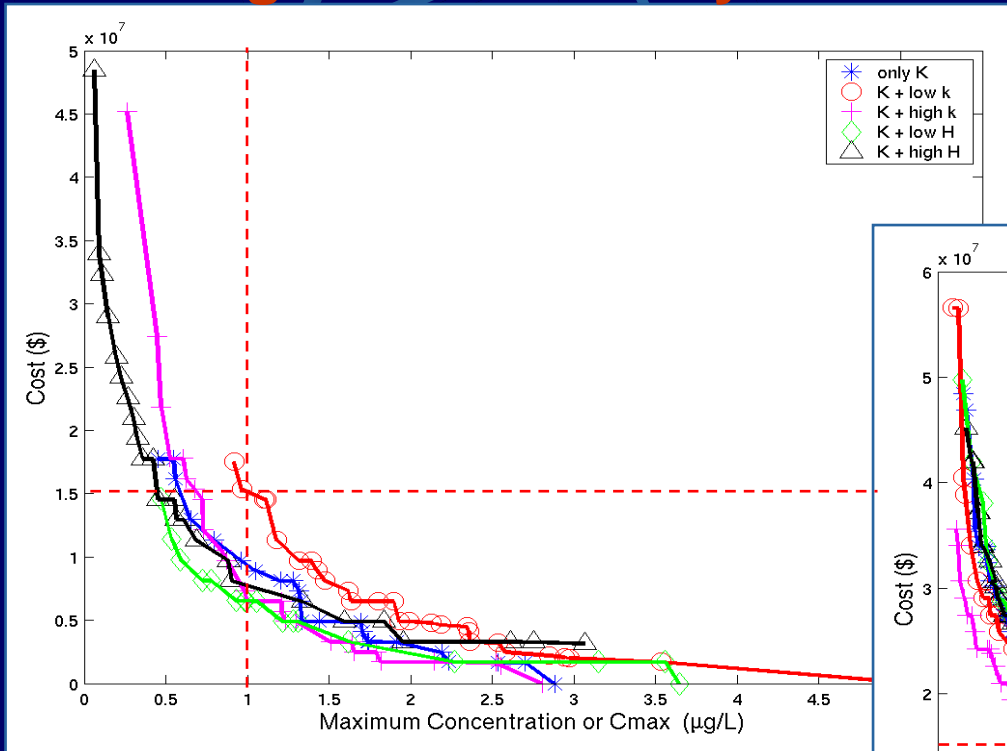
abchan@eng.fsu.edu

<http://www.eng.fsu.edu/~abchan>

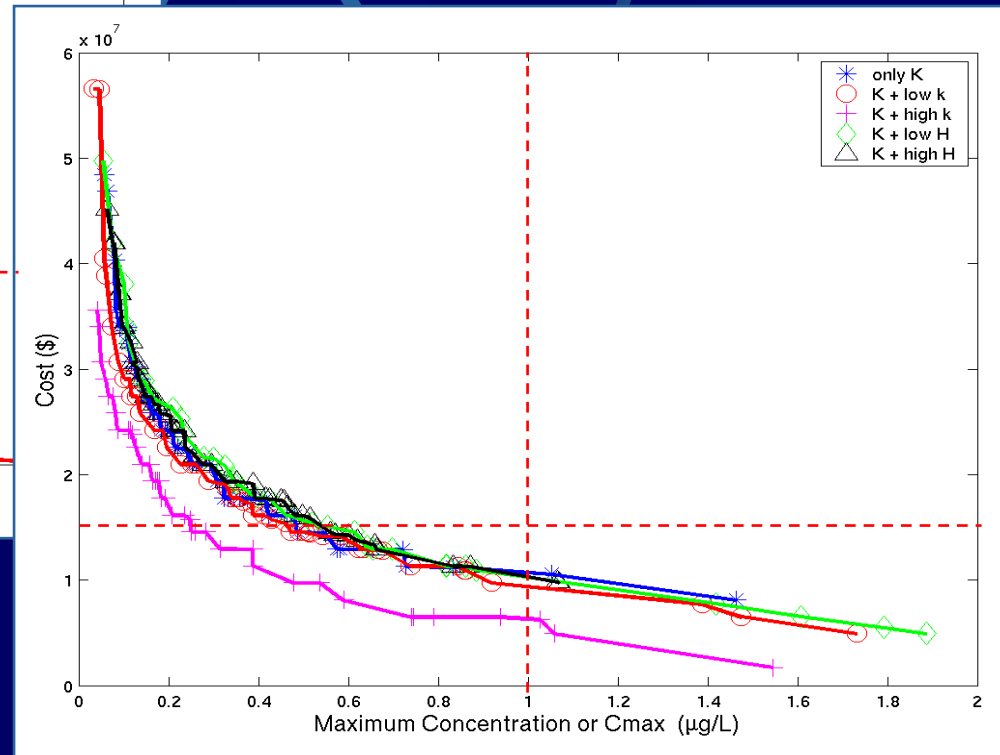


Comparison: All Cases

High K uncertainty



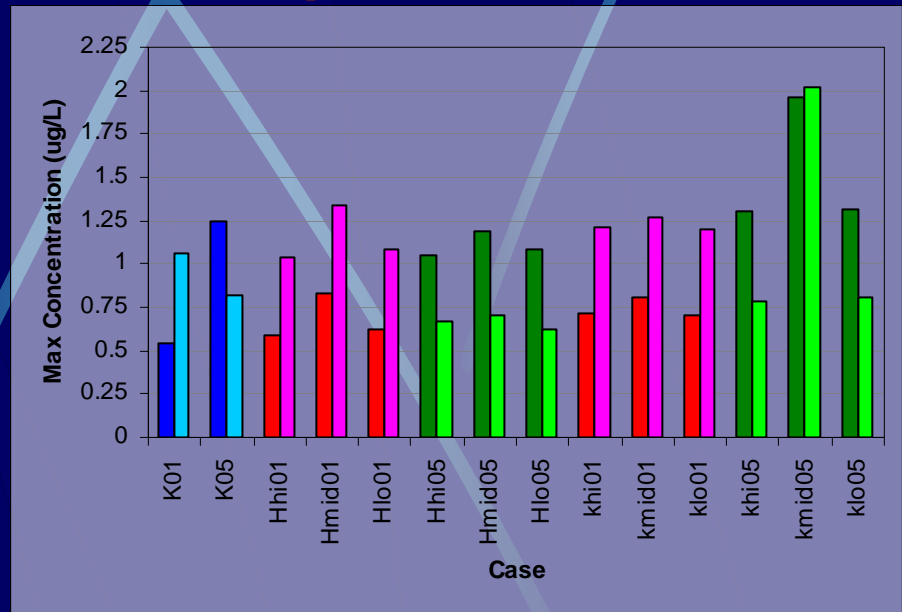
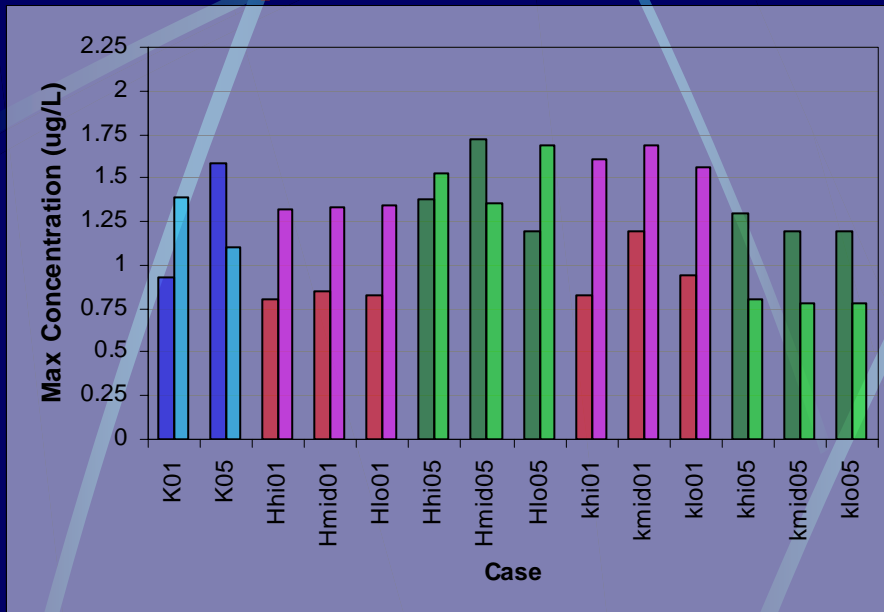
Low K uncertainty



Clean-up Levels of Designs

Cost-Optimal ($C_{max} = 1 \text{ ug/L}$)

C_{max} -Optimal (Cost = \$15M)



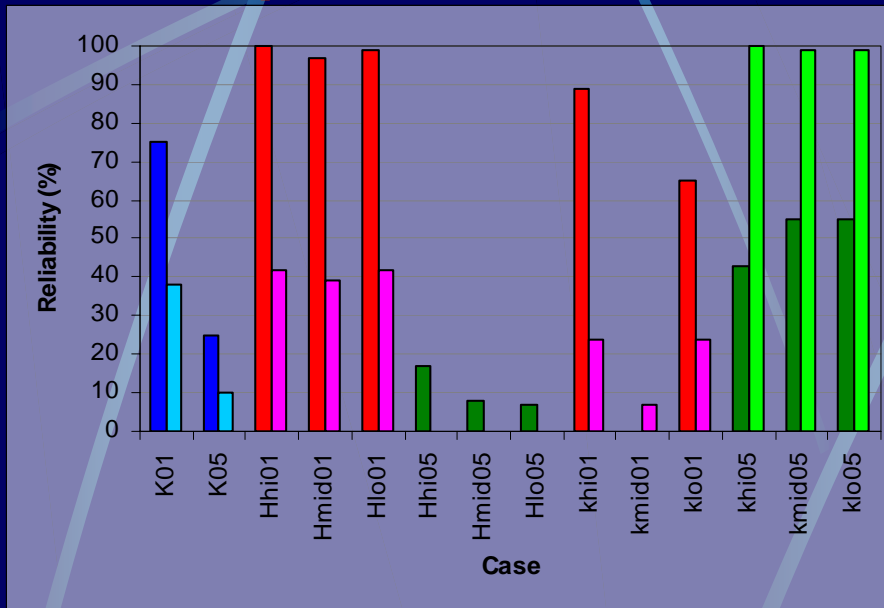
All cases evaluated on same K uncertainty scenarios

Left bars: Low K variance ($\sigma^2 = 0.1$)

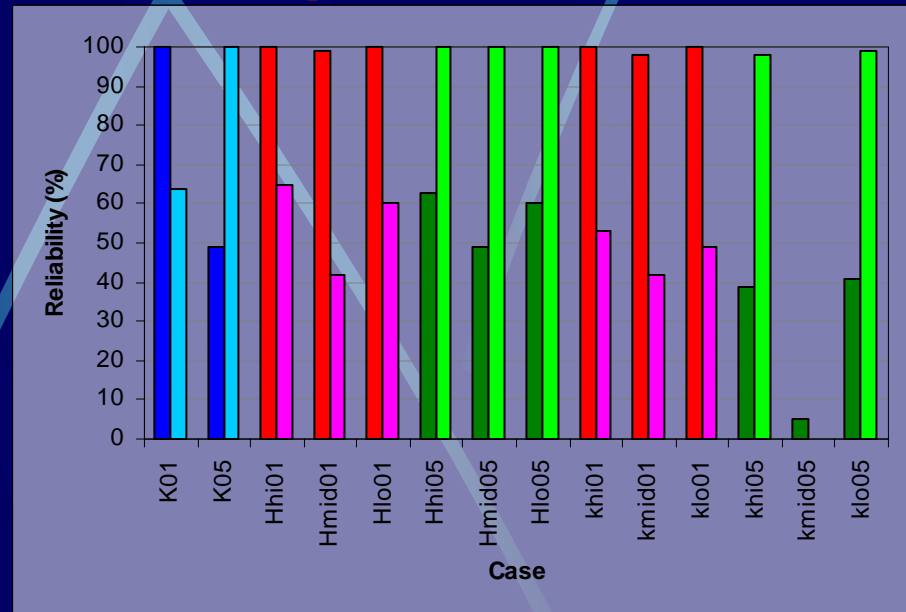
Right bars: High K variance ($\sigma^2 = 0.5$)

Reliability of Designs

Cost-Optimal ($C_{max} = 1 \text{ ug/L}$)



C_{max} -Optimal (Cost = \$15M)



All cases evaluated on same K uncertainty scenarios

Left bars: Low K variance ($\sigma^2 = 0.1$)

Right bars: High K variance ($\sigma^2 = 0.5$)